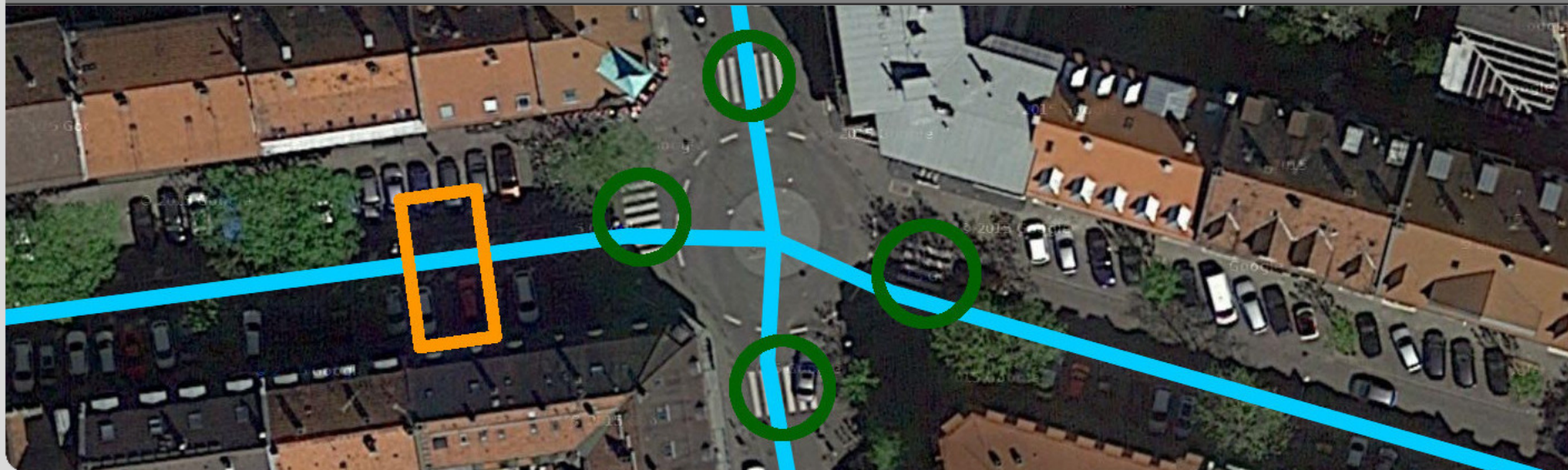


Zebra Crossing Detection from Aerial Imagery Across Countries

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INSTITUTE FOR ANTHROPOMATICS AND ROBOTICS – COMPUTER VISION FOR HUMAN COMPUTER INTERACTION



Motivation



Motivation



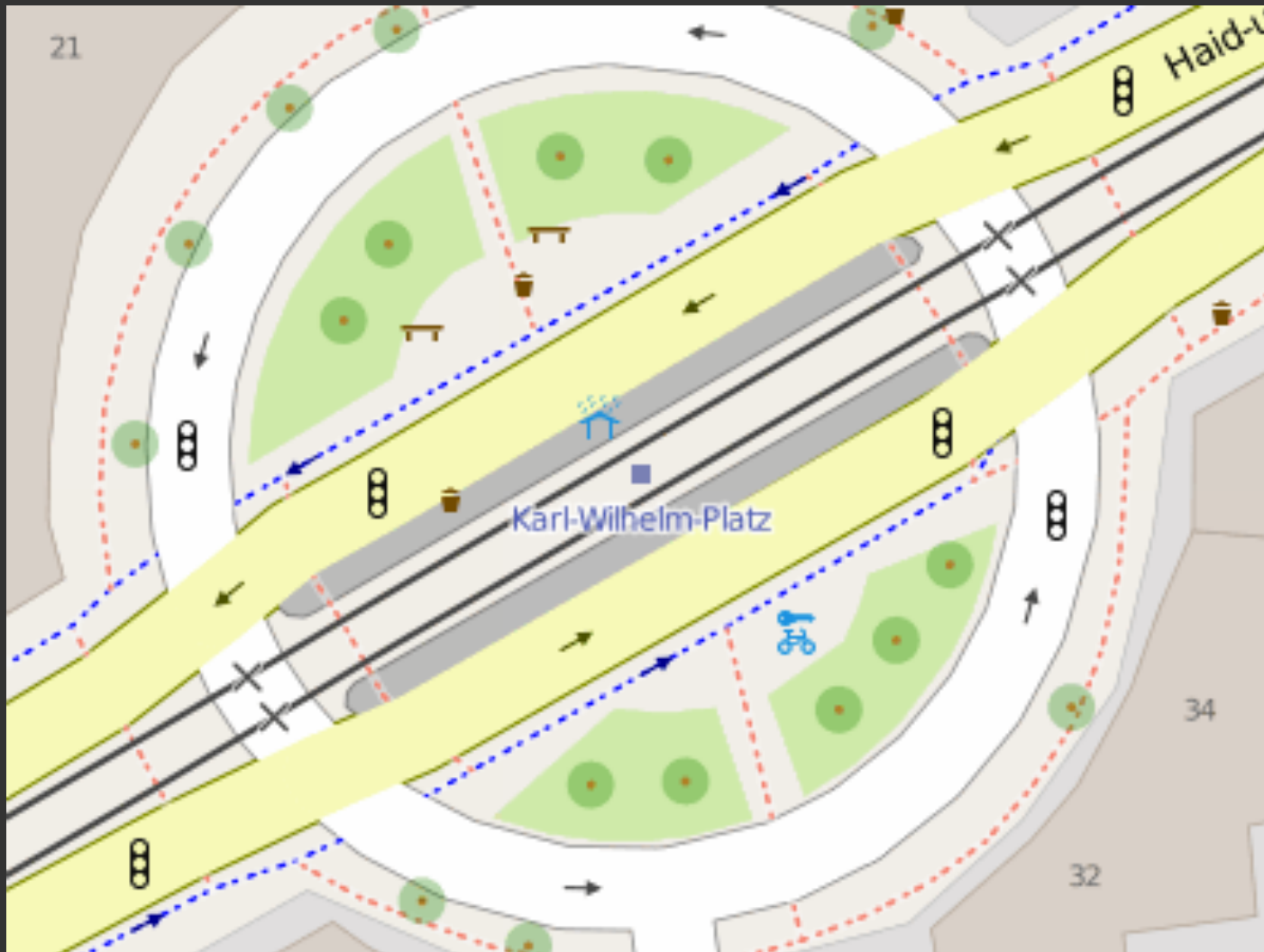
Motivation



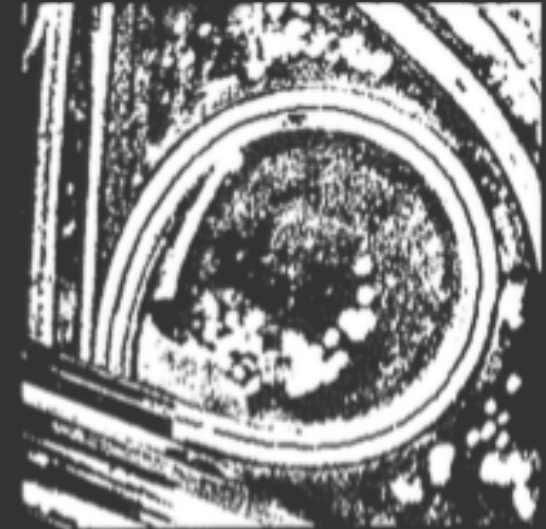
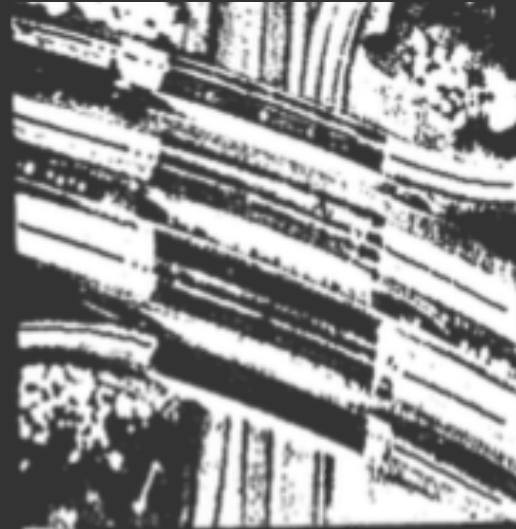
Motivation



Motivation

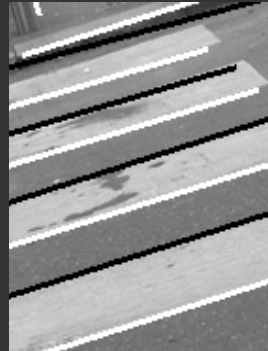


Related Work



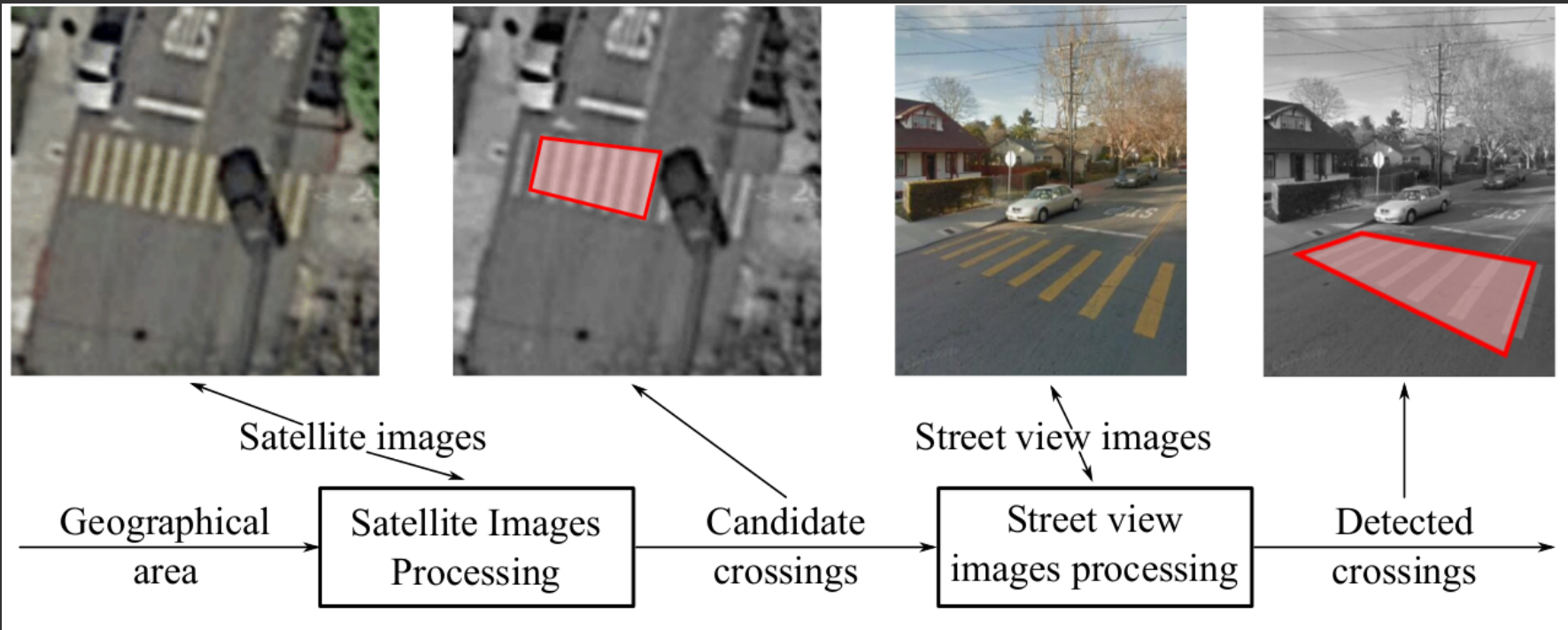
- Lynn H. Quam: Road Tracking and Anomaly Detection in Aerial Imagery. Supported by DoD/ARPA (1978)
- 1-3 feet/pixel ground resolution!

Related Work – Street Level



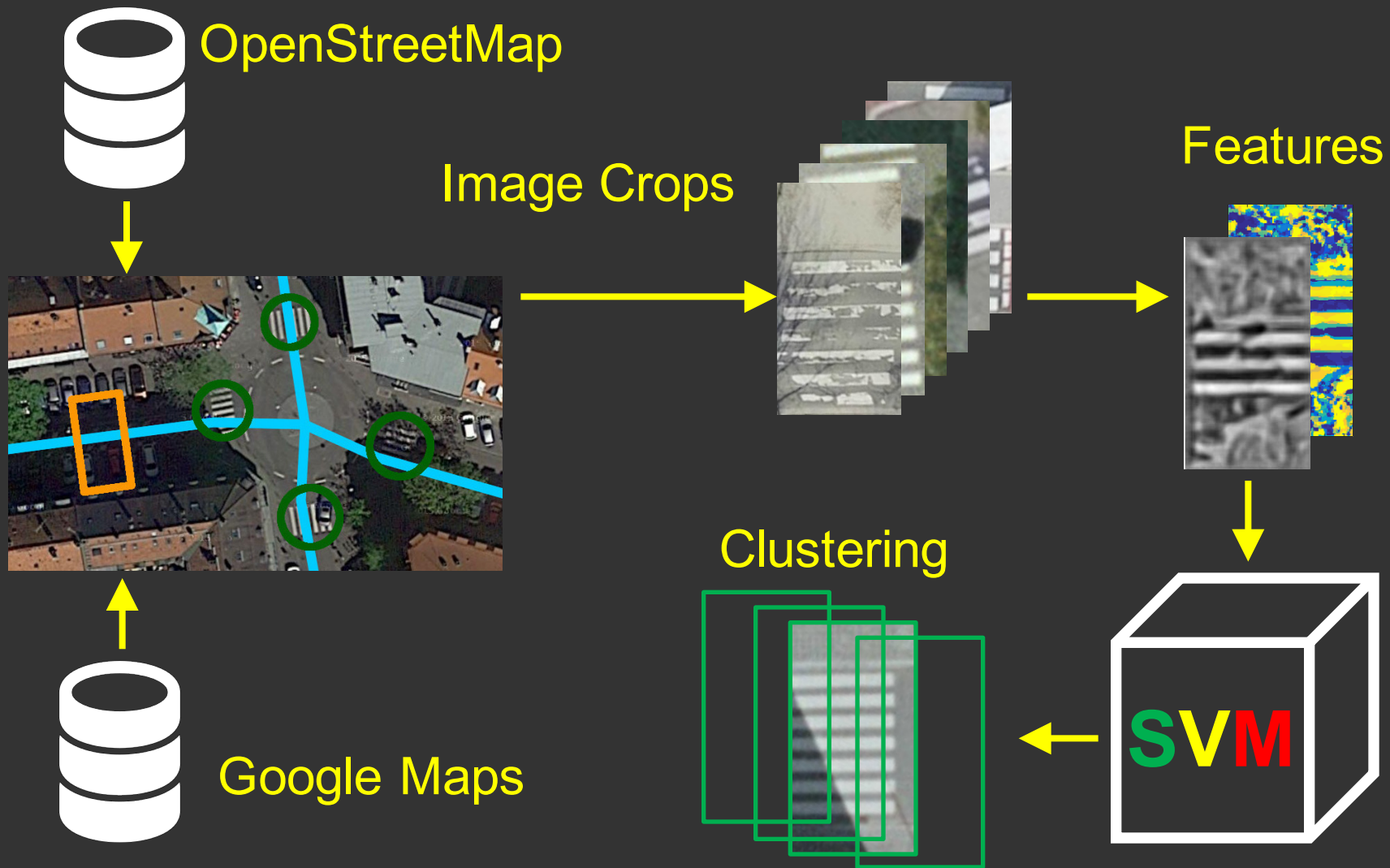
- Stephen Se: Zebra-Crossing Detection for the Partially Sighted (CVPR 2000)
- Coughlan et al.: A Fast Algorithm for Finding Crosswalks Using Figure-Ground Segmentation (ECCVW 2006)
- Ivanchenko et al.: Detecting and Locating Crosswalks Using a Camera Phone (CVPRW 2008)
- Ahmetovic et al.: Zebralocalizer: Identification and Localization of Pedestrian Crossings (MobileHCI 2011)

Related Work – Aerial Imagery

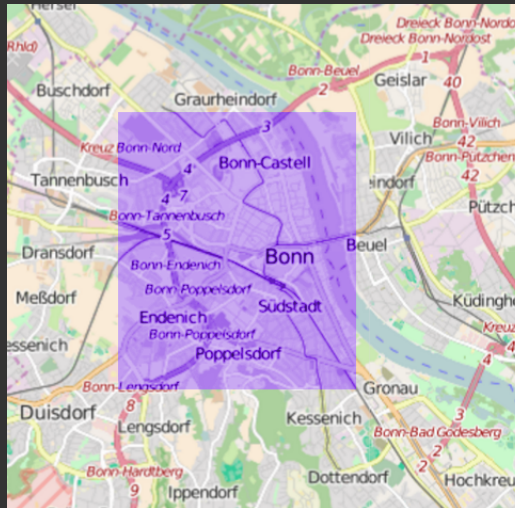


- Ahmetovic et al.: Zebra Crossing Spotter: Automatic Population of Spatial Databases for Increased Safety of Blind Travelers (ASSETS 2015)

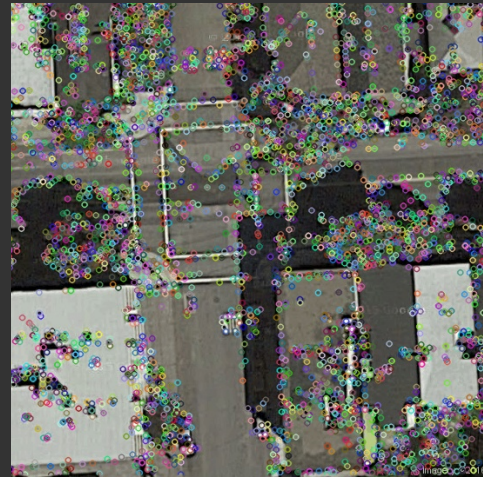
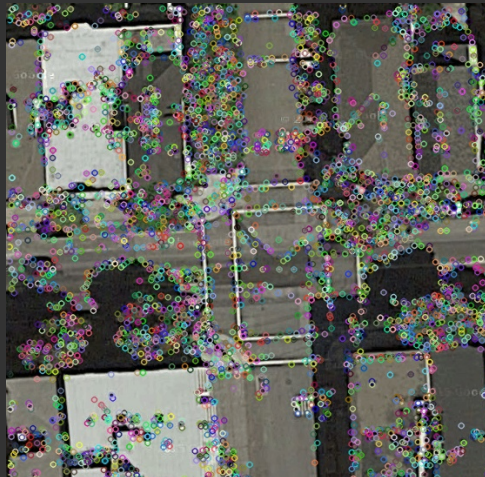
Algorithm – Overview



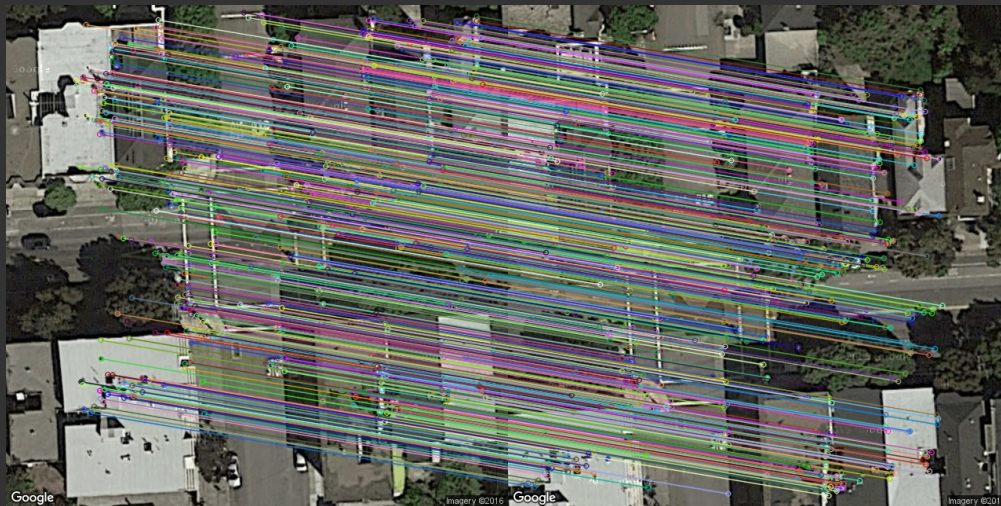
Algorithm – Street Data



Algorithm – Geodetic Datum



Specify Coordinate- Δ
Calculate Features

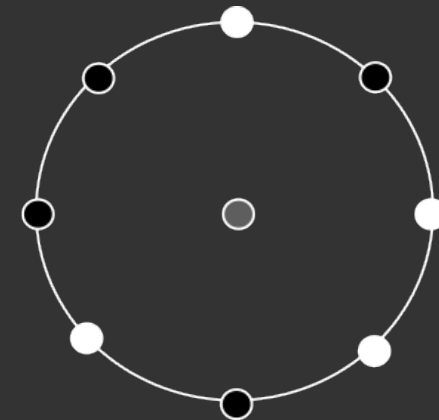


Match Features

Algorithm – HOG and LBP



Histogramm of Oriented Gradients



10110100

Local Binary Patterns

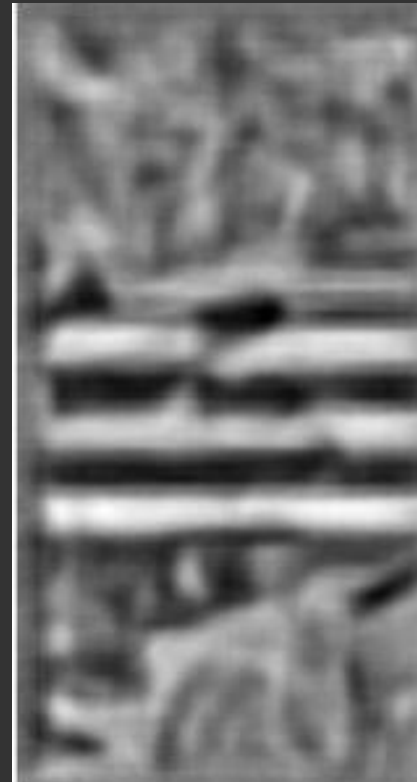
Algorithm – Feature Space



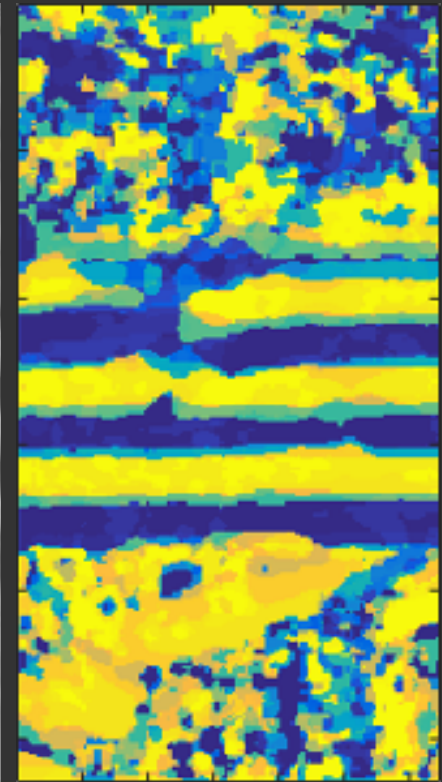
Original



HOG

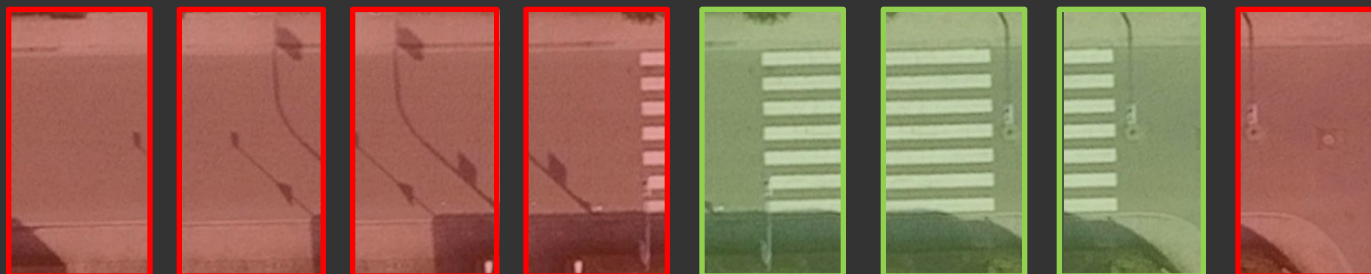
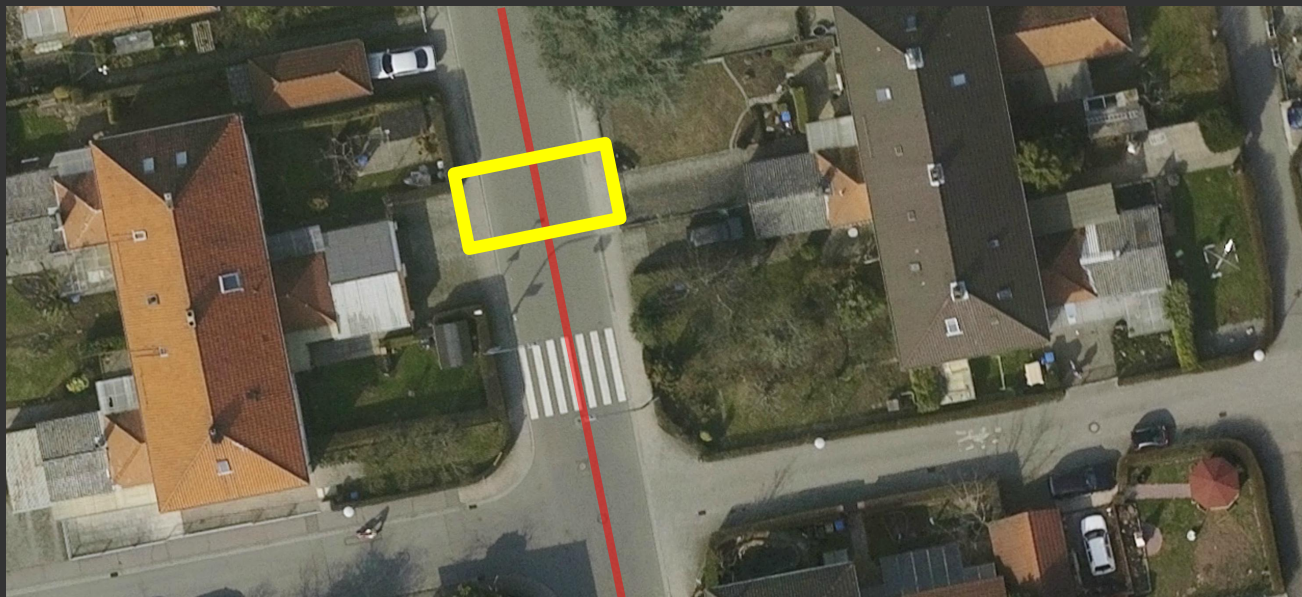


HOGgles

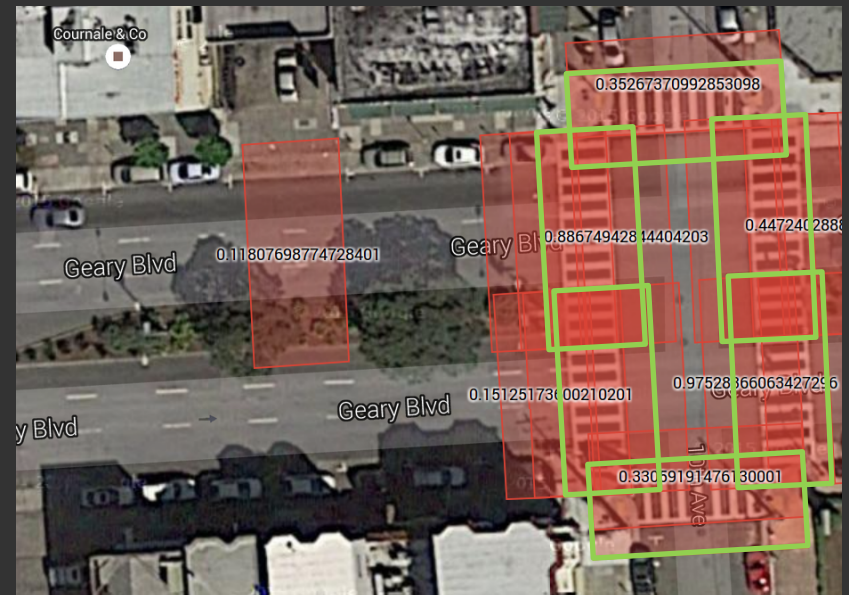
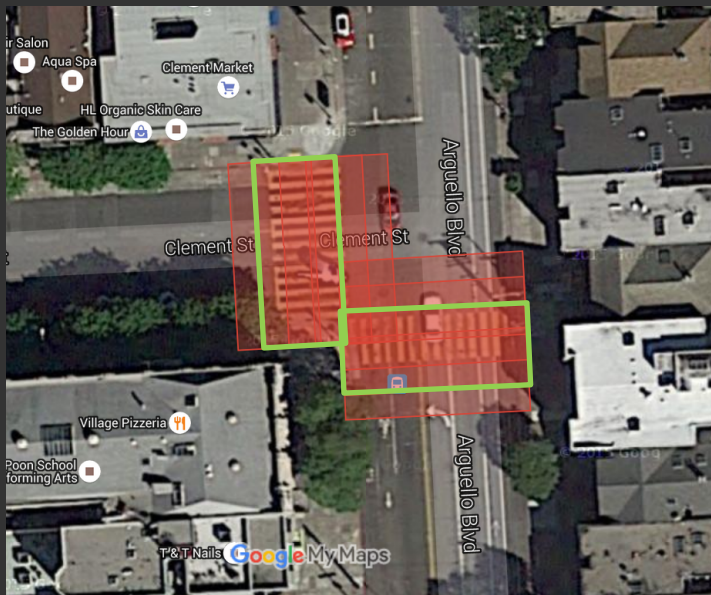


LBP

Algorithm – Detection



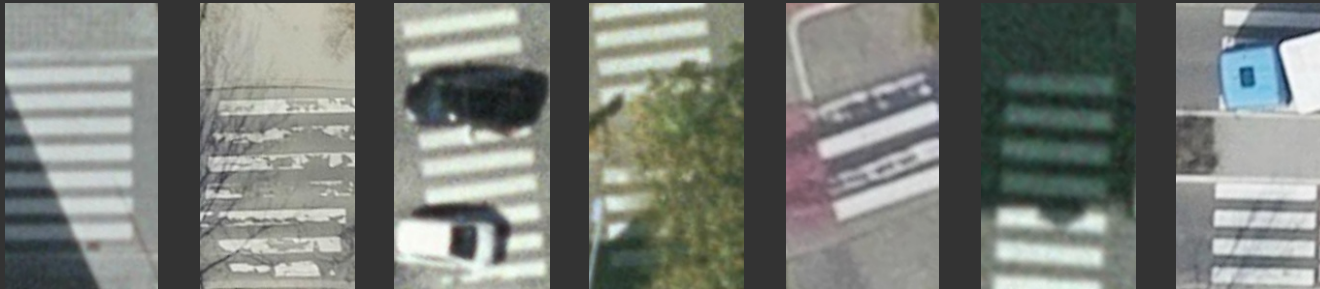
Algorithm – Clustering



Simple clustering algorithm:

- direction of subsequent detections
 - distance of subsequent detections
 - detection score
- ## Removes most outliers and separates zebra crossings nicely!

Evaluation



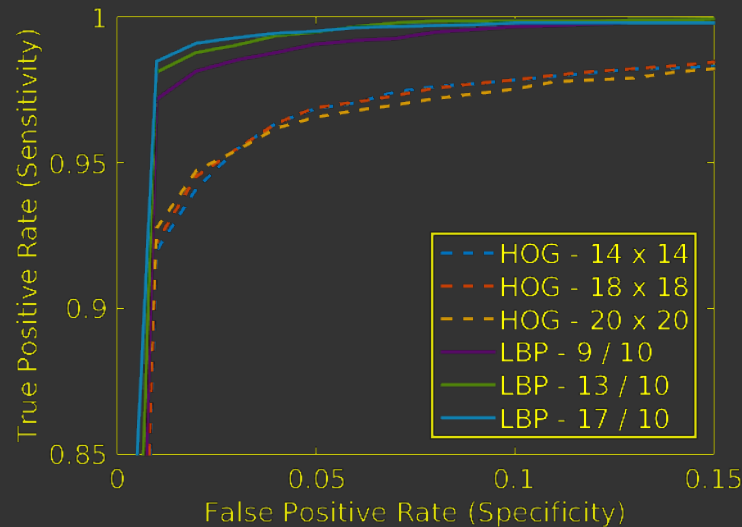
■ Collected dataset:

- various urban and rural German regions
- ~10km of road surface
- ~3100 zebra crossings
- various defects: shadows, occlusions, deteriorations, illumination changes
- resolution varies from 5-10cm/pixel

■ Train SVM on even data split

■ Augmentation: mirror horizontally and vertically

Evaluation – 5-Fold Cross-Validation



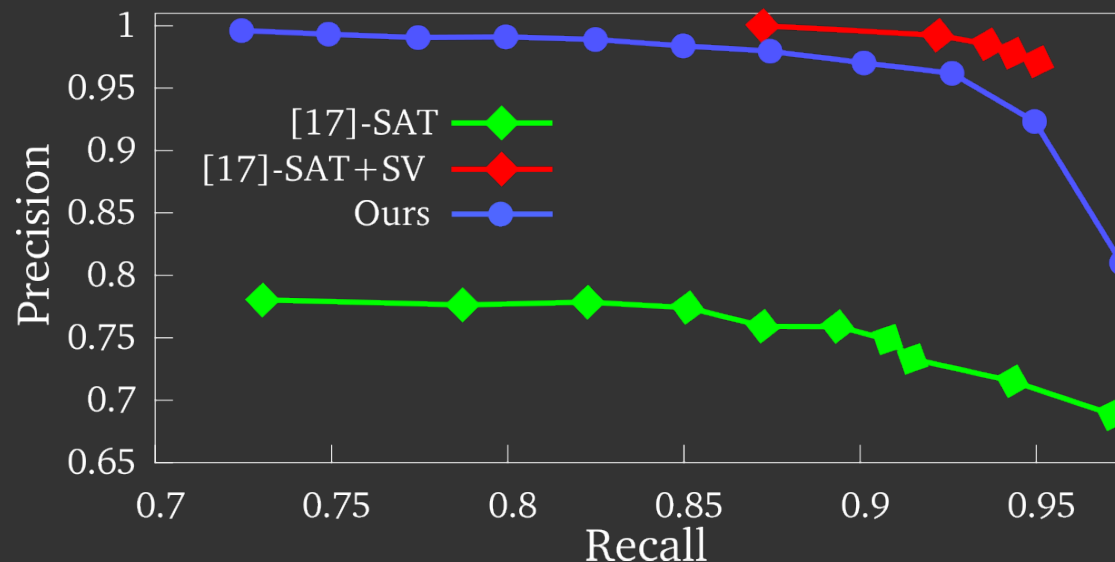
Method	Precision	Recall	Accuracy	Avg.-Prec
HOG ^{30×30} -lin	74.8	93.1	92.4	94.43
HOG ^{20×20} -RBF	95.2	96.2	98.9	97.99
LBP ^{17/10} -lin	99.4	97.4	98.4	99.56
LBP ^{17/10} -RBF	99.7	97.0	98.3	99.56

Evaluation – San Francisco

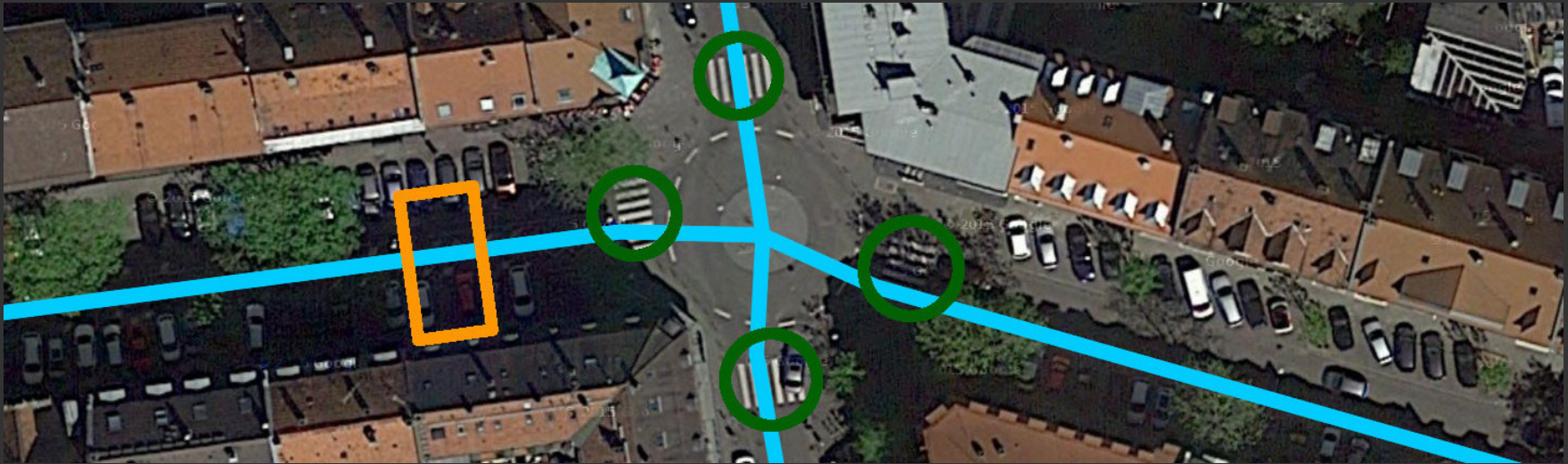


	Precision	Recall
[17]-SAT	68.8	97.2
[17]-SV	97.2	97.8
[17]-SAT+SV	97.2	95.0
Ours	96.2	95.7
Ours-PRE	98.9	38.4

[17] Ahmetovich et al.:
 Zebra Crossing
 Spotter: Automatic
 Population of Spatial
 Databases for
 Increased Safety of
 Blind Travelers

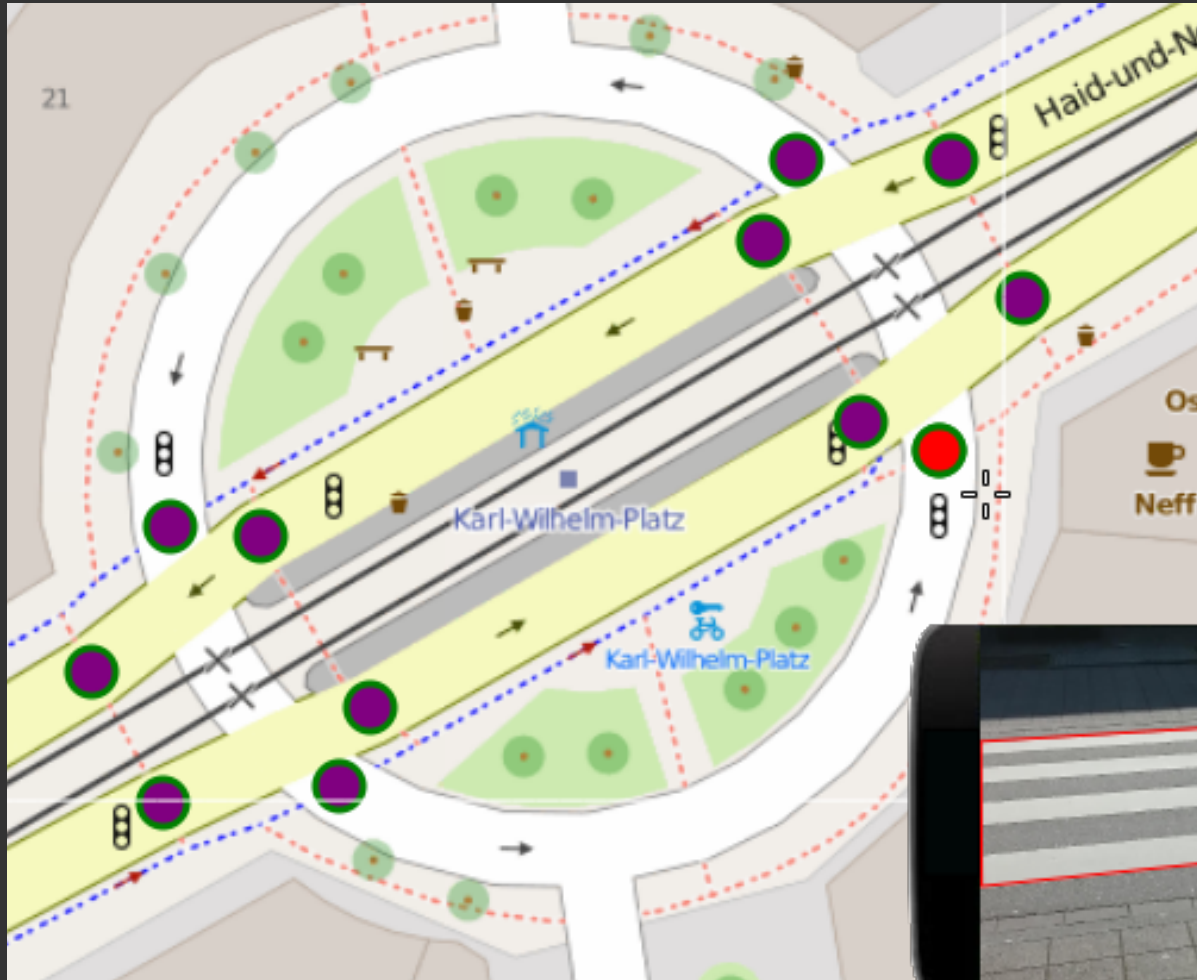


Conclusion



- Zebra crossing detection in aerial imagery
- Achieve competitive results (even across countries)
- Improvement in availability and quality of geospatial data
- Use for navigation and guidance applications

Future Work



Questions?

■ Thank you for your attention!



Image Sources

- #2: “Don’t judge too quickly”, Source Unknown
- #3: https://en.wikipedia.org/wiki/Pedestrian_crossing
- #4: <http://www.thebeatles.com/album/abbey-road>
- #5: <https://mntransportationresearch.org/2014/03/27/cell-phone-app-guides-blind-through-work-zones/>
- #11: AeroWest (<http://www.aerowest.de/>)
- #13:
<http://sipi.usc.edu/database/database.php?volume=misc&image=12#top>
- #22: <https://1951club.wordpress.com/2011/08/28/well-cross-that-street-when-we-come-to-it/>